

Non-standard Conflict analysis for solving the Job shop problem

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ROC group : Recherche Opérationnelle/Optimisation Combinatoire/Contraintes



LAAS-CNRS

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Bordeaux, France

Boolean Satisfiability (SAT)

Problem

- Boolean variables (atoms)
- Propositional logic formula (often CNF)
- Literals: a, \bar{a}
- Clauses: $(\bar{a} \vee \bar{f} \vee g), (\bar{a} \vee \bar{f} \vee g), (\bar{a} \vee \bar{b}), (b \vee \bar{c} \vee g)$

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SAT Solving

- DPLL : Backtracking in Tree Search + Unit Propagation
- Conflict-Driven Clause Learning (CDCL) : DPLL + Learning
- But also :
 - Adaptive branching heuristics (weight conflicting literals)
 - Restarts
 - Simplifications
 - Forget clauses
 - Incrementality
 - ...

Given a clause C of arity n . If $n - 1$ literals are false then set the last one to be true.

Example

$$(h \vee \bar{o} \vee \bar{j} \vee n)$$

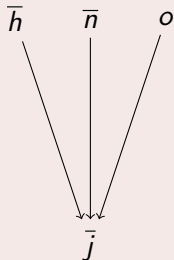
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Example



$$\begin{aligned} & (h \vee \bar{o} \vee \bar{j} \vee n) \\ & \equiv \\ & (\bar{h} \wedge o \wedge \bar{n}) \rightarrow \bar{j} \end{aligned}$$

Conflict-Driven Clause Learning

	f		

$$\bar{a} \vee \bar{f} \vee g$$

$$\bar{a} \vee \bar{b} \vee \bar{h}$$

$$a \vee c$$

$$a \vee \bar{i} \vee \bar{l}$$

$$a \vee \bar{k} \vee \bar{j}$$

$$b \vee d$$

$$b \vee g \vee \bar{n}$$

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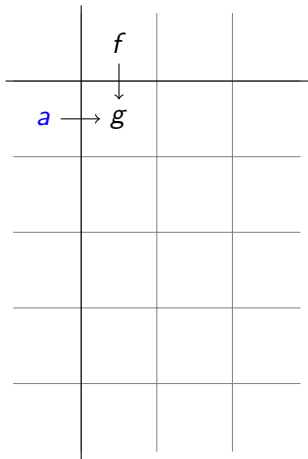
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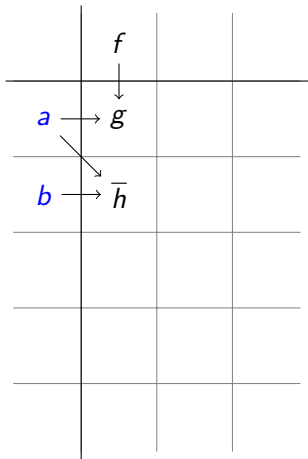
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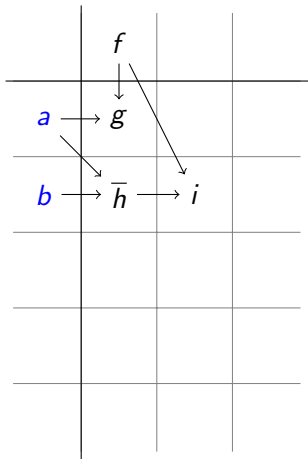
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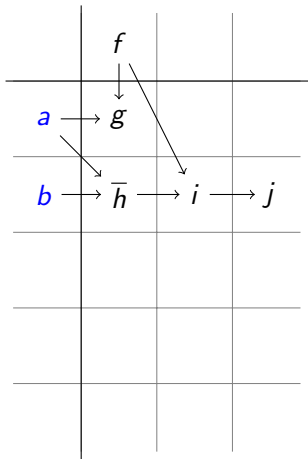
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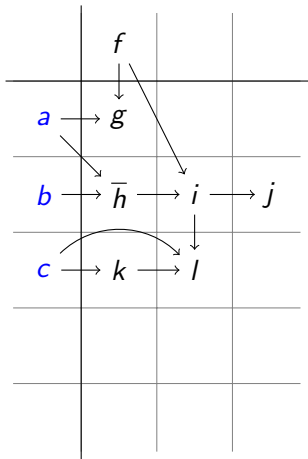
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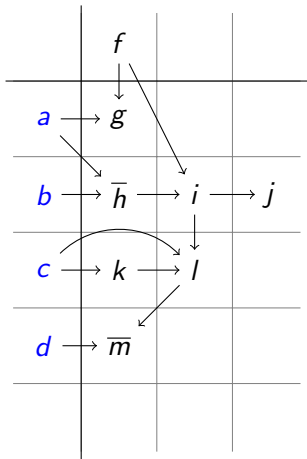
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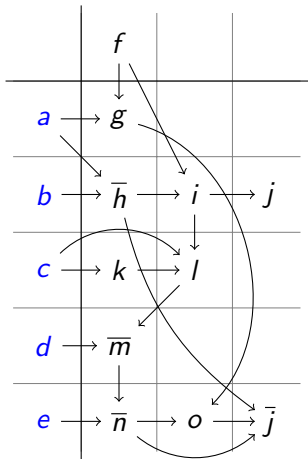
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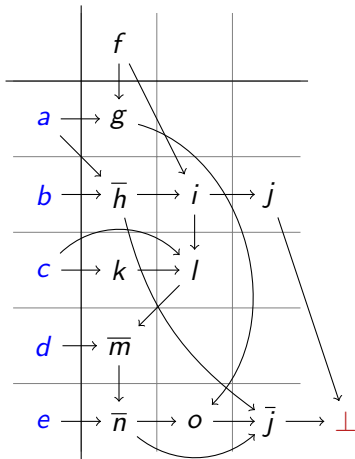
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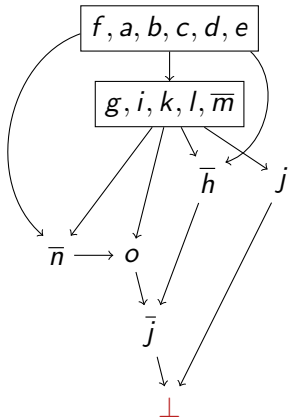
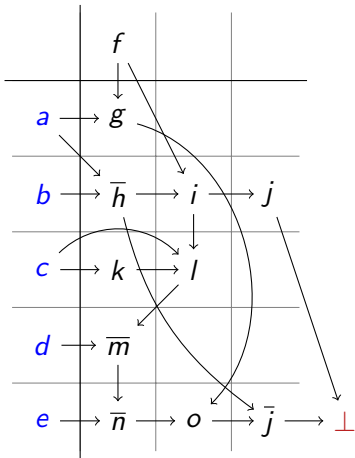
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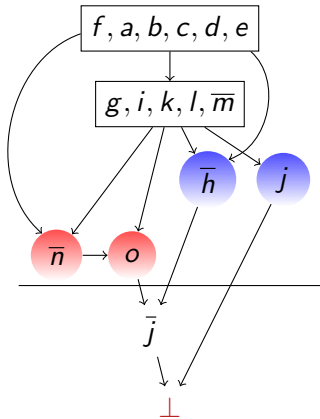
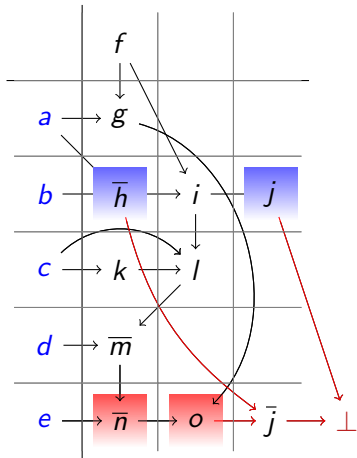
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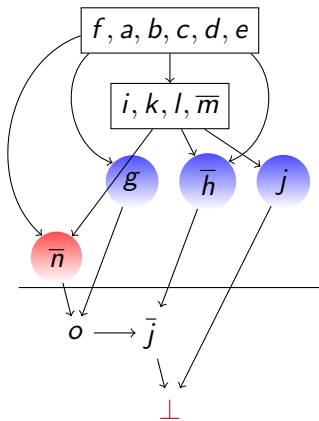
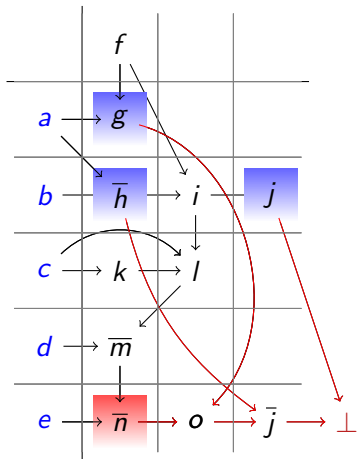
Conflict-Driven Clause Learning



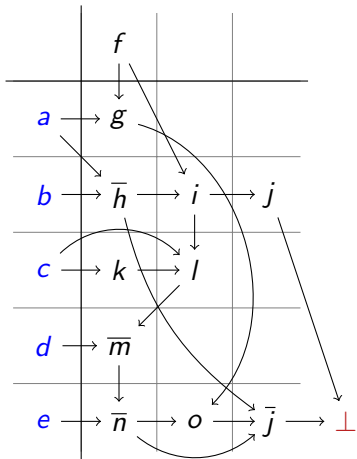
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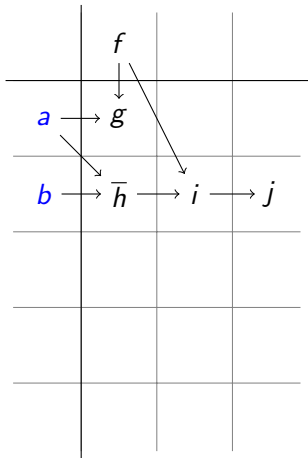
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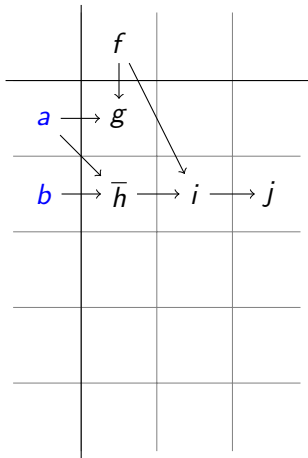
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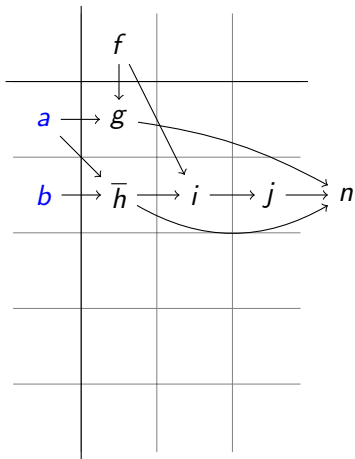
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SAT & CP :

- Can we get the best from both approaches?
- to encode into SAT or to use global constraints?
 - A key concept in hybrid solvers : **Explanations**

An explanation is a set of atomic constraints triggering a failure/filtering.

example

Cardinality Constraint : $\sum_{i=1}^n x_i \leq k ; D(x_i) = \{0, 1\}$.

$x_i \leftarrow 1$ is pruned if we already have k appearances of the value 1.

$$\{x_j \leftarrow 1 \mid D(x_j) = \{1\}\} \rightarrow x_i \leftarrow 1 .$$

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Given a variable X , s.t. $D(X) = \{v_1, v_2, \dots, v_n\}$

- The Direct Encoding : $\llbracket X = v_i \rrbracket$
 - $\llbracket X = v_1 \rrbracket \vee \llbracket X = v_2 \rrbracket \dots \vee \llbracket X = v_n \rrbracket$
 - $\neg \llbracket X = v_1 \rrbracket \vee \neg \llbracket X = v_2 \rrbracket$
 - $\neg \llbracket X = v_1 \rrbracket \vee \neg \llbracket X = v_3 \rrbracket$
 - ..
- The order Encoding : $\llbracket X \leq v_i \rrbracket$
 - $\neg \llbracket X \leq v_1 \rrbracket \vee \llbracket X \leq v_2 \rrbracket$
 - $\neg \llbracket X \leq v_3 \rrbracket \vee \llbracket X \leq v_3 \rrbracket$
 - .. $\neg \llbracket X \leq v_{n-1} \rrbracket \vee \llbracket X \leq v_n \rrbracket$

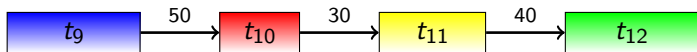
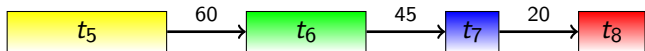
Job shop Scheduling Problem



Problem description

- A set of non-preemptive tasks

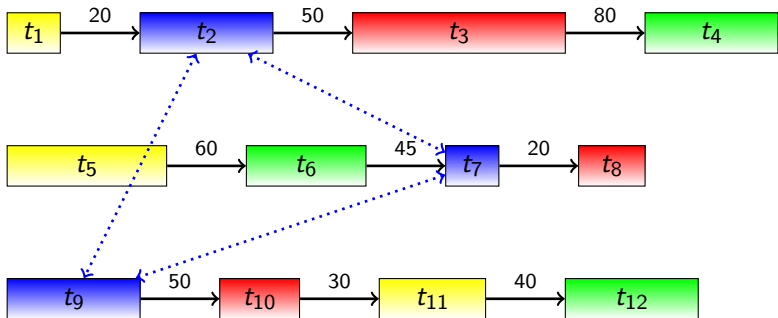
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Problem description

- A set of non-preemptive tasks
- Organized in jobs (sequences)

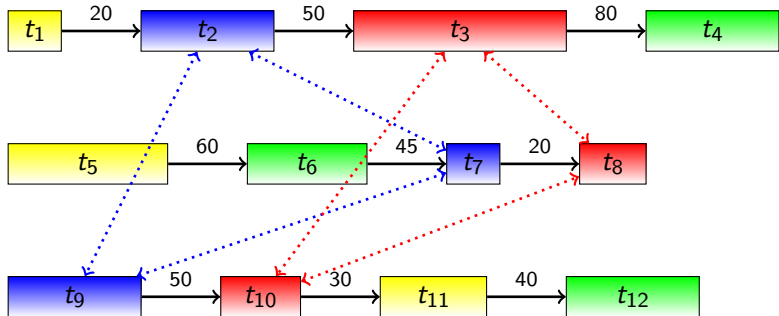
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Problem description

- A set of non-preemptive tasks
- Organized in jobs (sequences)
- Requiring one of m disjunctive resources

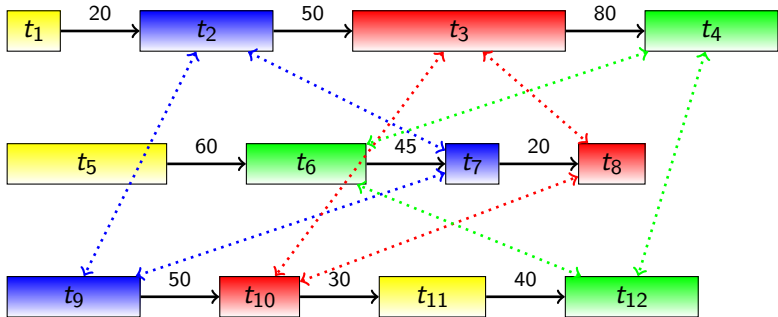
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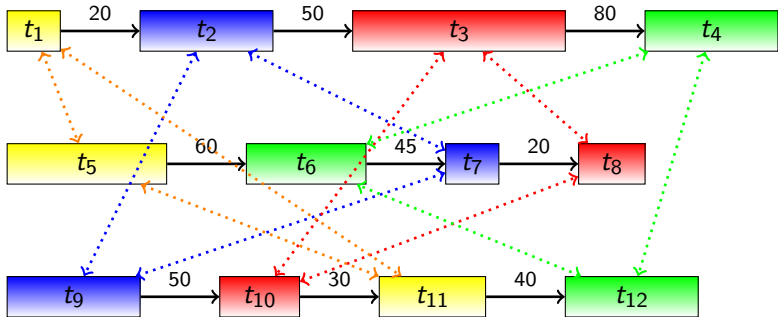
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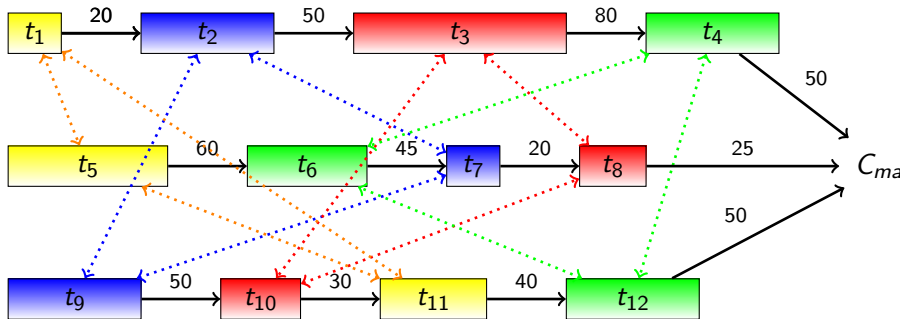
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- Organized in jobs (sequences)
- Requiring one of m disjunctive resources
- Objective: minimize the total duration (C_{max})

- Precedence constraints: $t_i + p_i \leq t_{i+1}$.
- Binary Disjunctive constraints: $b_{ij} = \begin{cases} 0 \Leftrightarrow t_i + p_i \leq t_j \\ 1 \Leftrightarrow t_j + p_j \leq t_i \end{cases}$

Explaining $X + p \leq Y$

Failure

$$\llbracket X \geq l_X \rrbracket \wedge \llbracket Y \leq u_Y \rrbracket \rightarrow \perp$$

Pruning

$$\begin{aligned} \llbracket Y \leq u_X + p \rrbracket &\rightarrow \llbracket X \leq u_X \rrbracket \\ \llbracket X \geq l_Y - p \rrbracket &\rightarrow \llbracket Y \geq l_Y \rrbracket \end{aligned}$$

Explaining the disjunctive Constraint

$$b = \begin{cases} 1 & \Leftrightarrow X + p \leq Y \\ 0 & \Leftrightarrow Y + p' \leq X \end{cases} \quad (3.1)$$

Failure

$$b \wedge \llbracket X \geq l_X \rrbracket \wedge \llbracket Y \leq u_Y \rrbracket \rightarrow \perp \text{ or} \\ \neg b \wedge \llbracket Y \geq l_Y \rrbracket \wedge \llbracket X \leq u_X \rrbracket \rightarrow \perp$$

Pruning

$$b \wedge \llbracket Y \leq u_X + p \rrbracket \rightarrow \llbracket X \leq u_X \rrbracket \\ b \wedge \llbracket X \geq l_Y - p \rrbracket \rightarrow \llbracket Y \geq l_Y \rrbracket \\ \neg b \wedge \llbracket X \leq u_Y + p' \rrbracket \rightarrow \llbracket Y \leq u_Y \rrbracket \\ \neg b \wedge \llbracket Y \geq l_X - p' \rrbracket \rightarrow \llbracket X \geq l_X \rrbracket$$

$$\llbracket Y \geq l_Y \rrbracket \wedge \llbracket X \leq u_X \rrbracket \rightarrow \llbracket b = 1 \rrbracket \\ \llbracket X \geq l_X \rrbracket \wedge \llbracket Y \leq u_Y \rrbracket \rightarrow \llbracket b = 0 \rrbracket$$

Dealing with large domains

Suppose $|D(X)| = 10^6$

- Generate 10^6 atoms only to encode the domain of X
- Check 10^6 clauses just for the consistency of the domain of X

→ **Solution** : Lazy generation

→ **Much better !** but not that good!

- Redundancy of clauses : suppose that $a < b < c$ and $\llbracket X \leq a \rrbracket$, $\llbracket X \leq c \rrbracket$, and $\neg \llbracket X \leq a \rrbracket \vee \llbracket X \leq c \rrbracket$ are already generated. If $\llbracket X \leq b \rrbracket$ needed to be generated, then add
 - $\neg \llbracket X \leq a \rrbracket \vee \llbracket X \leq b \rrbracket$
 - $\neg \llbracket X \leq b \rrbracket \vee \llbracket X \leq c \rrbracket$

→ $\neg \llbracket X \leq a \rrbracket \vee \llbracket X \leq c \rrbracket$ becomes redundant

- Possibly we will end up with a large number of generated atoms

- Deciding the set of boolean variables is sufficient to decide the problem!
- What about learning nogoods defined only over these variables?
- What to do to bound assignments $\llbracket X \leq v \rrbracket$ coming from explanations?

Virtual Literals

- Literals of the form $\llbracket X \leq v \rrbracket$ are no longer represented by integers
- We propose a data structure called 'Virtual Literal' containing these fields :
 - is_a_bound_literal : bool
 - is_a_lower_bound : bool
 - value : integer
 - id_variable : integer
- for instance with a 64bit integer encoding, one can do the following :

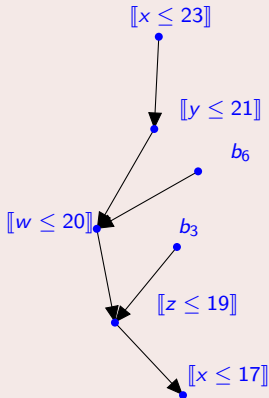
1/0	1/0		
is_a_bound_literal	is_a_lower_bound	value (32 bits)	id_variable (30 bits)

- Backward explanations : Whenever a domain change occurs during propagation, do not generate a clause! Just record the constraint triggering that propagation.
- During conflict analysis, we ask constraints to explain themselves.
- Whenever a bound literal occurs, replace it with its reason.

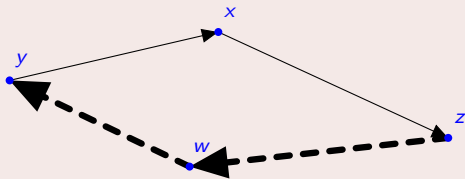
- Suppose that during conflict analysis a (virtual) literal $\llbracket X \leq 17 \rrbracket$ has already been explored and afterwards a (virtual) literal $\llbracket X \leq 23 \rrbracket$ occurs.
- One can consider $\llbracket X \leq 17 \rrbracket$ as a valid explanation for $\llbracket X \leq 23 \rrbracket$ since $\llbracket X \leq 17 \rrbracket \rightarrow \llbracket X \leq 23 \rrbracket$ is always correct.
- \rightarrow Do not explore $\llbracket X \leq 23 \rrbracket$, just drop it.

Improvements : Cycles

Suppose that when exploring $\llbracket X \leq 17 \rrbracket$, $\llbracket X \leq 23 \rrbracket$ occurs.



Improvements : Cycles



lemme

If in the predecessors of an upper (lower) bound literal $\llbracket X \leq v \rrbracket$ ($\neg \llbracket X \leq v \rrbracket$) there exists a literal of the form $\llbracket X \leq v' \rrbracket$ ($\neg \llbracket X \leq v' \rrbracket$) then a 'precedence' cycle has appeared in the constraint graph and has at least two disjunctions.

Theorem

The set of disjunctions appearing in such cycle is a valid nogood.

- A new method to tackle large domain SAT encoding
- A perfect framework to exploit lazy explanations
- Several improvements are being proposed
- Learning from cycles opens new learning perspectives but should be carefully studied as it doesn't guarantee UIP.

Thank you!